

METHODOLOGY FOR OPTIMIZATION OF SHELL STRUCTURES

by

Paul Dysh

General Dynamics Data Systems Division

For Presentation at the

42nd Annual Conference

of

Society of Allied Weight Engineers, Inc.

Atlanta, Georgia 21-23 May 1984

Permission to publish this paper in full, or in part, with full credit to the author and the Society may be obtained by request to:

**S.A.S.E., Inc.
344 East 7th Street
Chico, Miss. 39209**

The Society is not responsible for statements or opinions expressed in papers or discussions at its meetings.

ABSTRACT

This paper outlines the major analysis modules that could be used to optimally size shell of revolution structures. Specifications for the modules are provided. Both empirical and finite-element methods are considered. For selected optimization examples, the modules are organized into flow diagrams indicating I/O functions and human intervention requirements. Examples of optimal analysis results are presented.

INTRODUCTION

This paper describes an expert system for the computer-aided engineering and design of toroidal and waffle, integral cylinder, cone shell structures. Figure 1 shows a typical shell configuration to which this system applies.

The secondary structure in Figure 1 comprises the bosses, bolted flanges, thick ring, and split line or longitudinal members. Typical loads on the structure are body loads applied to one bolted flange while the other is fixed, and local loads on the bosses. The moment, axial, and transverse load components for both types of loading are indicated in Figure 1.

Starting with an input design specification, the function of the expert system is to perform the following tasks with a minimum of human intervention:

- Determine worst-case internal design loads.
- Select and size an optimum shell design configuration.
- Size secondary structures.
- Provide user with visibility over, and facilities for verification of, all phases of the sizing and design process.
- Generate CAD-based detailed design drawings.

SYSTEM OVERVIEW

Figure 2 shows an overview of the expert system. The following are some of its features.

Internal shell loads are generated on the basis of a tailored or unstiffened shell. The unstiffened shell has uniform constitutive properties; the tai-

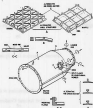


Figure 1. Typical shell configuration including secondary structure and showing typical load components.



Figure 2. Overall system.



Figure 11. Internal load, GEN.

Numerous user variables and design definition parameters generated by ISOPPT are output on other data sheets not shown here.

Figure 12 shows a wafer flat pattern layout including a lens. It was produced by a Computer-Driven CAD/CAM system file generated by CYSDX. RAAPROM output initialized CYSDX.

SUMMARY AND CONCLUSIONS

The expert system described in this paper:

- Provides significant cost and time-to-design savings for the specialized layout and wafer structures it addresses.
- Can be used as a model for development of a similar or a related expert system.
- Captures expert knowledge and significantly reduces human intervention.
- Is extremely user friendly.
- Can be readily expanded to incorporate other sizing and optimization routines and criteria.

- Provides a high level of user visibility, accountability, and verifiability over all of its functions.
- Outputs a complete status analysis and mass properties report, including documentation describing all variables, algorithms, and analytical functions.

Most of the code described in this paper is fully developed and tested — some of it is in the early stages of development.

The expert system is an implementation of a design-for-CAD-and-CAM philosophy. In this case, extension of the system to design-for-CAM should also be feasible.

APPENDIX SPECIFICATIONS FOR MAJOR PROGRAMS

1. Internal Load Generation



Figure 11. Fan pattern layout CHEY output.

GENI — Computes distributed loads in a cylinder-cone shell structure. Externally applied loads can be classically distributed or point loads. Shell is monocoque except for optional longitudinal members, which may be located at any angle with respect to top dead center. Computes average and maximum in-plane compression-tension line loads and associated shear for all analyzed elements. It also computes:

- All internal reactions.
- Load peaking factors when point loads or reactions are used on the shell.
- Axial components of internal pressure that act on the conical part of the structure. This is in addition to hoop loads.
- Moment and axial load relief in the primary shell structure due to the presence of longitudinal members.

Inputs

- Geometry, including all section lengths and radii, analytical element sizes, longitudinal flange cross-section properties, and shell structure unstressed-out-of-flange-equivalent, monocoque plate thickness and Young's modulus.
- For each load case applied internal body bending, axial, torsional, and transverse loads, plus all point loads.
- Internal or external pressure.
- Load reaction points or areas.
- Overriding load symmetry: one for no load symmetry, two for two-way or diametrical symmetry, and four for four-way symmetry.

- Selection of whether average or maximum analytical-element load intensities are to be passed shell analysis programs.

Outputs

- Distributed in-plane tension/compression load intensities and associated shear flow in each analyzed element for all load cases.
- Worst-case distributed design loads which can be alternatively be used as input to the shell analysis programs.
- Overall axial, torsional, and bending displacements of the complete shell structure, including longitudinal members.
- Reactions in mounting surfaces and point attachments.

FEM1 — A pre- and post-processor for SAPROTM. Generates a three-dimensional FEM model of the shell based on an overall shell geometry, longitudinal member parameters, stiffness-equivalent skin thickness, and Young's modulus for each shell analytical element as generated by the detailed shell analysis programs. Extracts element in-plane loads from SAPRO output for input to shell analysis.

Inputs

Same as those for GENI with addition of different skin thickness and Young's modulus for each analytical element.

Outputs

Same as those for GENI.

1. Preliminary Shell Analysis

ISOPTS — Optimally sizes an isoprid shell structure element using user-defined or statistically selected analytical elements. The shell is a cylinder-cone. Sizing is based on GENI loads and specified design criteria. Following are some of the features of ISOPTS:

Automatic computation of cross-section properties of different rib types, including stress-dependent effective skin (i.e., the greater the stress, the less is the skin contributing to cross-section properties). The cross-sections can be types produced by machining or chemical milling. The chemically milled cross-sections require auto-

static curve fitting routine to establish closed-form solutions for cross-section properties. Reference cross-sections are also used as baselines for establishing proportions between different parts of the cross-section.

Margin computations include:

- Four alternative general instability margins based on References 1, 3, 6, 7, and 12.
- Two alternative accountual high-cycle fatigue (RCF) margins based on Reference 8, etc.
- Material stress and yield strength properties.
- Rib crippling.
- Skin buckling (Reference 1) secondary stiffened and unstiffened skins.
- Low-cycle fatigue (LCF).
- Resonant frequencies and mode shapes under load and no load conditions are computed per References 4, 5, and 10.
- Estimates of number of load cycles to failure due to crack growth are made on basis of Reference 13.
- Computation of total and unit area shell weights are based on nominal, maximum, and average dimensions for separate and combined skin thickness, rib width, and plate thickness. The nominal weight is based on tolerances halfway between nominal and maximum. The unit area weights determined for the selected element is used to compute a total shell weight having constant rib widths, skin thickness, and plate thickness.
- ESOPT1 will determine the minimum weight structure by: (1) meeting specified margin, resonance frequency, and stiffness requirements; and (2) iterating through the matrix of minimum, maximum, and incremental values specified for rib width, skin thickness, plate thickness, and number of longitudinal ribs. The algorithm employed for this purpose establishes a margin floor which is raised above zero by successively increasing either rib width or skin thickness, depending on which produces the greatest floor increment per given weight increment. The process is terminated when the floor is above zero. Newton Raphson techniques are used to speed the computation.

- Margins for rib crippling, skin buckling, LCF, and material properties are computed using minimum cross-section and skin dimensions while nominal dimensions are used to compute instability margins. Any tolerance criteria can, however, be specified to override these default conditions.
- RCF margins for skin panels are computed by ESOPT1 for a matrix of minimum, nominal, and maximum skin thicknesses and secondary rib widths to select the critical value. The most critical values in this case are not necessarily produced at minimum gaps.
- Temperature dependent material properties can be separately specified or computed by ESOPT1 for selected range of materials.
- A detailed data printout is provided by ESOPT1. It includes margin, mass properties, and invariant parameter summaries.

Inputs

- Shell mold line geometry.
- Manufacturing tolerances.
- Minimum and maximum values, increments for rib width, skin thickness, and plate thickness; and number of longitudinal ribs.
- Limit, ultimate, knock-down, and margin factors.
- Margins, resonant frequencies, and/or stiffness requirements to be used as sizing criteria.
- Initial crack size and life cycle requirements.
- Rib cross-section type and reference cross-section.
- Material properties or material name and temperature.
- Analytical element to be optimized and worst-case design loads for uniform shell.

Outputs

- Detail data printout, including mass properties, margin summary, modal analysis, invariant parameters, stress, stiffness, etc.
- Tables: A matrix or plots of margins, weights, and resonant frequencies vs. rib width, skin thickness, plate thickness, and number of longitudinal ribs.

- User-selected traces of comparisons of significant margins, stresses, stiffness, and/or maximum frequencies. These can be used by the analyst to perform direct numerical checks referencing source material.

WALPFTN — Optimally sizes a waffle shell structure element using user, or automatically selected, analytical elements. The shell is a cylinder-cone. Sizing is based on GEM1 loads and specified design criteria.

The features of WALPFTN are similar to those of EIGNFTN except for the following changes:

- One of the general instability comparisons from Reference 1 is replaced by a comparison based on Reference 2.
- Inputs must include ring spacing.
- General instability is skin-buckling dependent; consequently, positive skin buckling margins must be specified with general instability margins.

1. Detailed Shell Analysis

EIGNFTN — This code is similar to EIGNFT1 with the following exceptions:

- All analytical elements of the shell are optimally sized and overall weights are based on a sum of element weights. Individual elements do not, therefore, have to be selected. The element sizing involves selection of optimum skin thickness and rib width while holding the plate thickness and number of longitudinal ribs constant for each run.
- Element-data printer is limited to margin and cross-section parameter values.
- Inputs from GEM1 are replaced by inputs from FEM1. Also EIGNFTN creates an output file of stiffness-equivalent element thicknesses and Young's modulus for input to FEM1. This output is used recursively to update FEM1 internal loads.
- Outputs include optimized structure design definition and explain design loads and shell constitutive parameters at beams, lock rings, and flanges. A three-dimensional SAP88 finite-element is also a by-product.

WALPFTN — This is similar to EIGNFTN, with the differences described under WALPFT1.

4. Secondary Structures Analysis

4A. Beam Analysis

STRUBOSS — This program performs the following functions:

- Automatically models a planar FEM multi-sided ring truss frame structural equivalent of a beam or cut out in a cylinder-cone shell. The FEM model includes influence of surrounding shell as well as tension/compression and shear flow loads derived from the local in-plane load environment (i.e., from FEM1).
- Performs a mini FEM analysis using the above model and computes stresses and stress margins for all (at least 48) critical points on the model. Mini FEM is incorporated in STRUBOSS.
- Computes stress concentration factors (Reference 14) for circumferential holes in beams and at fillets on attachment ribs. These are used in stress margin computations for these points.
- Stresses and stress margins are computed for external local loads applied to the beam. This computation is based on Reference 7 which is fully implemented in STRUBOSS. Superposition is used to add these Walker-analysis results to those from Mini FEM.

On the current STRUBOSS version the beams must be circular or square in plan layout and must be (or assumed to be) located in a shell area free from the influence of other beams, the lock ring and bolted flanges.

Inputs

- Material properties.
- Beam geometry: rim ID, OD, width, thickness; mounting flange ID thickness; flange holes, locations, etc.
- Loads from FEM1, local applied loads, and pressure.
- Beam location on shell plus local in-plane load environment from FEM1 and local skin thickness and rib widths from EIGNFTN or WALPFTN.

- Number of ribs (rib width contributing to form rim effective cross-section).
- Initial rib width and type plus skin thickness terminating on boss. Default values for these taken from ISOPFTN or WAPFTN. At least two diametrically aligned ribs are assumed to intersect the boss in both the longitudinal and circumferential directions.
- Rib width increments.

Outputs

- Lengths and orientations of all ring cross members comprising the boss or wheel crown.
- Loads on all cross members including start and end moments, axial forces, and shears.
- Linear and angular deflections at each node of model.
- Stress concentration factors.
- Stresses and margins in boss (ID and OD) on mounting holes and in free ribs terminating on boss.
- Rib widths of free terminating ribs that produce positive stress margins at rib attachment.

4B. Initial Flange Analysis

FLG — The flange analysis is based on a series of sub-routines which perform the following functions:

- Two mini FEM models are automatically created: one with a rib in line with a hole and one with the hole centerline midway between ribs. The models include a default offset of one-eighth of the bolt diameter for the location of the reaction point between the bolt head and the flange. Head-to-toe action is also assumed on the flange face.
- The mini FEM analysis is run to produce internal loads and deflections for both models.
- After the bending moments in the bolt are reduced by a 1.5 plasticity reduction factor, combined stresses and their margins are computed at nine critical points in the bolt, flange, and shell structure for both models.
- Negative margins are corrected by human intervention in the current software version.

These can include increasing rib width, local skin thickness, or bolt diameter, or decreasing bolt spacing.

Inputs

- Flange geometry, including bolt circle diameter, bolt size, bolt hole diameter, bolt length, flange thickness, and flange ID and OD.
- Initial shell local rib width and skin thickness from ISOPFTN or WAPFTN.
- Wheel local in-plane shell loads from FEM1.
- Material properties for bolt and flange. Note: Default properties for flange are the same as those of the shell.
- Radial reaction point offset and head-toe reaction point offset, if other than default values.
- Plasticity reduction factor, if not 1.5.

Outputs

- Models: geometry, cross-section properties, internal load, deflections, and resultant factors.
- Summary of stresses and margins at nine critical locations for both FEM models.

4C. Kick Ring Analysis

KICKR — This program is used to size the kick ring at the cone-cylinder intersection. A classical analysis is used to compute internal moment axial and transverse loads in the kick ring from which rib-cap stresses and margins are computed for both the ring and longitudinal ribs that terminate on it. A microscope shell has to be assumed in this analysis. Numerical accuracy of computations must be increased with decreasing cone angle below 15° .

Inputs

- Material properties.
- Local shell rib width and skin thickness from ISOPFTN or WAPFTN.
- External body loading, transverse, axial, and torsional loads from input specification.
- Initial kick ring cross-section properties, including offset of its circumferential axis from conical plane of shell.
- Internal pressure.

Outputs

- Internal moments, torsional, shear, and axial loads in ring and local longitudinal skin and ribs.
- Induced effective radial load components on ring.
- Stress and stress margins in ring caps and local longitudinal rib caps.

5. Graphics Generation

5A. Analytical-to-Physical Model Grid Mapping

CXWIN — This program maps the analytical element rib widths and skin thicknesses from **WAPWFTN** into arrays defining physical model rib widths and skin thicknesses. The number of longitudinal ribs and ring spacing in the physical model are also derived from **WAPWFTN**. The algorithm used in this program includes the following features:

- When a physical pocket is intersected by more than one analytical element, the selected rib width and skin thickness is taken from the analytical element having the greatest unassisted bending stiffness.
- Discontinuities between conical or conical and cylindrical sections are detected and the internal ring of the connecting section is located at the discontinuity.
- The material volume of the physical model is computed, from which weights are determined. These calculations can be at nominal dimensions or any combination of off-nominal dimensions for different parts of the rib-skin cross section. The mass properties should corroborate those from **ISOPFTN** and **WAPWFTN**.

CXRN — This is the Isoprid version of **CXWIN**. Its inputs come from **ISOPFTN**. Ring spacing input is not needed; however, the user must specify the locations of the first circumferential set of nodes in each conic section of the physical model.

5B. Automated Flat Pattern Layout

CNEXT — This is an expert system (Reference 16) for the automatic layout of the flat pattern of

an integral cylindrical or conical waffle structure, including its bosses. Boss bending fillets are automatically inserted to integrate bosses into the waffle structure (as, for example, they would normally be by and still machining operations). Procedures for boss installation include pattern recognition to determine which graphic entities are to be deleted and which are to be added. Extensive geometric analysis and testing are required to implement these and related procedures.

Inputs

- Half-rib widths, skin thicknesses, corner fillet radii, and all pocket coordinate data from **WAPWFTN** (These are used for the layout of the basic grid of waffle panels).

REFERENCES

1. Beckus, H., "Strength of Stiffened Curved Plates and Shells," *Handbook of Structural Stability*, Part VI, NASA TN 3786, July 1958.
2. "Buckling of Thin-Walled Circular Cylinders," NASA SP-8007, August 1968.
3. Isoprid Design Handbook, NASA CR-124075, February 1973.
4. Szechenyi, E., "Approximate Methods for the Determination of the Natural Frequencies of Stiffened Curved Plates," *Journal of Sound Vibration* 14(3), 401-418, June 1978.
5. Leissa, A.W., "Vibration of Plates," NASA SP-160, 1969.
6. Bruhn, E.P., "Analysis and Design of Flight Vehicle Structures," Tri-State Offset Co., 1963.
7. Spink, R., et al., "Isoprid Structural Team and Stability Analysis," *Journal of Aircraft*, Vol. 13, No. 10, Oct. 1976.
8. "Structural Design for Acoustical Fatigue," Douglas Aircraft Co., Long Beach, California, Report AD 425 408, Oct 1963.
9. Wichman, K.R., et al., "Local Stresses in Spherical and Cylindrical Shells Due to External Loading," *Welding Research Bulletin* 187, August 1965.
10. Ewins, R.D., "Formulas for Natural Frequency and Mode Shape," Van Nostrand Reinhold Co., 1979.
11. Roark, R.J. and Young, W.C., "Formulas for Stress and Strain," 3rd Edition, McGraw-Hill Book Co., 1975.

12. Peterson, J.P., "Buckling of Half-Round Cylinders in Axial Compression and Bending — a Review of Test Data," NASA TN-0-1561, Dec 1969.
13. Kells, S.C. and Burton, J.M., "Fracture and Fatigue Control in Structures — Applications of Fracture Mechanics," Prentice-Hall, 1971.
14. Peterson, R.L., "Stress Concentration Factors," John Wiley & Sons, 1975.
15. SAP-88 Series of Structural Analysis Programs, Version 04.08 Jan 1983, Structural Analysis Programs Inc., El Cerrito, California.
16. Kiyoh, P., "Expert System for Layout of a Flat Plate of a Wall Structure Containing Stoves," Sixth Annual International Computer Users Conference, 1984.